

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	15	(342/25e).CCLS.	US-PGPUB; USPAT; IBM_TDB	OR	OFF	2005/02/10 15:01
L3	136	(342/64).CCLS.	US-PGPUB; USPAT; IBM_TDB	OR	OFF	2005/02/10 15:01
L4	784	(342/357.06).CCLS.	US-PGPUB; USPAT; IBM_TDB	OR	OFF	2005/02/10 15:48
L5	1625	match\$4 same ((geographic\$4 map) near1 (information data))	US-PGPUB; USPAT; IBM_TDB	OR	ON	2005/02/10 15:50
L6	294	5 same imag\$4	US-PGPUB; USPAT; IBM_TDB	OR	ON	2005/02/10 15:50
L7	61	6 same time	US-PGPUB; USPAT; IBM_TDB	OR	ON	2005/02/10 16:03
L8	1	("5,335,072").PN.	US-PGPUB; USPAT; IBM_TDB	OR	OFF	2005/02/10 16:03
S1	290	(correlat\$4 match\$4) same imag\$4 same geographic\$4	US-PGPUB; USPAT; IBM_TDB	OR	ON	2005/02/10 10:44
S2	113	((correlat\$4 match\$4) same imag\$4 same geographic\$4) and gps	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 14:08
S3	114	((correlat\$4 match\$4) same imag\$4 same geographic\$4) same time	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 14:08
S4	41	((correlat\$4 match\$4) same imag\$4 same geographic\$4) same time and gps	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:52
S5	55	((correlat\$4 match\$4) same imag\$4 same geographic\$4) same record\$4	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:53
S6	1	("6741790").PN.	US-PGPUB; USPAT; USOCR; IBM_TDB	OR	OFF	2004/07/13 15:44
S7	1	"09/900321"	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:44
S8	41	((correlat\$4 match\$4) same imag\$4 same geographic\$4) same time and gps	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:53

S9	394	record\$4 same geograph\$4 same imag\$4	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:54
S10	0	(record\$4 same geograph\$4 same imag\$4) same simultaneous\$4	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:54
S11	0	(record\$4 same geograph\$4 same imag\$4) same simultaneously	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:54
S12	51	(record\$4 same geograph\$4 same imag\$4) same gps	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:54
S13	143	(record\$4 same geograph\$4 same imag\$4) same time	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:54
S14	34	((record\$4 same geograph\$4 same imag\$4) same time) same during	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:55
S15	14	((((record\$4 same geograph\$4 same imag\$4) same time) same during) and gps	US-PGPUB; USPAT; IBM_TDB	OR	ON	2004/07/13 15:55
S16	317	(correlat\$4 match\$4) same imag\$4 same geographic\$4	US-PGPUB; USPAT; IBM_TDB	OR	ON	2005/02/10 10:44
S17	130	S16 and gps	US-PGPUB; USPAT; IBM_TDB	OR	ON	2005/02/10 10:44
S18	6	(correlat\$4 match\$4) same imag\$4 same geographic\$4 same tag\$4	US-PGPUB; USPAT; IBM_TDB	OR	ON	2005/02/10 15:00


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<paragraph> match*
<paragraph> time <paragraph>
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1 Note on the existence of perfect maps

Reed, I.; Stewart, R.;

Information Theory, IEEE Transactions on , Volume: 8 , Issue: 1 , Jan 1962
 Pages:10 - 12

[\[Abstract\]](#) [\[PDF Full-Text \(320 KB\)\]](#) IEEE JNL

2 Navigation of mobile robots in corridor network environment based memorized robot's motion and omni-directional images

Lixin Tang; Yuta, S.;

SICE 2002. Proceedings of the 41st SICE Annual Conference , Volume: 4 , 5-7 2002

Pages:2376 - 2381 vol.4

[\[Abstract\]](#) [\[PDF Full-Text \(426 KB\)\]](#) IEEE CNF

3 A weight-based map matching method in moving objects databases

Huabei Yin; Wolfson, O.;

Scientific and Statistical Database Management, 2004. Proceedings. 16th International Conference on , 21-23 June 2004

Pages:437 - 438

[\[Abstract\]](#) [\[PDF Full-Text \(232 KB\)\]](#) IEEE CNF

4 Real-time data fusion on tracking camera pose for direct visual guid

Zhencheng Hu; Uchimura, K.;


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Pages:842 - 847

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5 Scan matching based on CLS relationships

Xu Zezhong; Liu Jilin; Xiang Zhiyu;

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Pages:99 - 104 vol.1

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6 A panorama-based technique for annotation overlay and its real-time implementation

Kouroggi, M.; Kurata, T.; Sakaue, K.; Muraoka, Y.;

Multimedia and Expo, 2000. ICME 2000. 2000 IEEE International Conference on , Volume: 2 , 30 July-2 Aug. 2000
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[\[Abstract\]](#) [\[PDF Full-Text \(420 KB\)\]](#) IEEE CNF

7 Vision system research for autonomous underwater vehicle

Xiaohai Yuan; Chenchang Qiu; Rongsheng Chen; Zhen Hu; Peilin Liu;

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8 Matching form lines based on a heuristic search

Bohnacker, U.; Schacht, J.; Yucel, T.;

Document Analysis and Recognition, 1997., Proceedings of the Fourth International Conference on , Volume: 1 , 18-20 Aug. 1997
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[\[Abstract\]](#) [\[PDF Full-Text \(512 KB\)\]](#) IEEE CNF

9 Extraction of parameters from a wavelet packet analysis for terrain matching

Popescu, B.; Costa, P.; Larzabal, P.; Clergoet, H.;

Time-Frequency and Time-Scale Analysis, 1996., Proceedings of the IEEE-SP International Symposium on , 18-21 June 1996
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10 Onboard real-time system for 3D urban environment reconstruction

Abuhadrous, I.; Nashashibi, F.; Laugeau, C.; Goulette, F.;

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11 **The principles of positioning with space-borne SAR images**

Chang Benyi; Fang Yong;

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Pages:1950 - 1952 vol.4

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12 **Oceans 2002 Conference and Exhibition. Conference Proceedings (No.02CH37362)**

Oceans '02 MTS/IEEE , Volume: 3 , 29-31 Oct. 2002

[\[Abstract\]](#) [\[PDF Full-Text \(2135 KB\)\]](#) [IEEE CNF](#)

13 **Eye detection using hybrid rule based approach and contour mappi**

Samad, S.A.; Hussain, A.; Teoh, A.;

Signal Processing and its Applications, Sixth International, Symposium on. 2001 , Volume: 2 , 13-16 Aug. 2001
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14 **Real-time normalization and feature extraction of 3D face data usin curvature characteristics**

Tae Kyun Kim; Seok Cheol Kee; Sang Ryong Kim;

Robot and Human Interactive Communication, 2001. Proceedings. 10th IEEE International Workshop on , 18-21 Sept. 2001
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15 **Real-time omnidirectional stereo for obstacle detection and trackin dynamic environments**

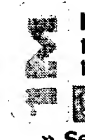
Koyasu, H.; Miura, J.; Shirai, Y.;

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 16 **Tracking players and a ball in soccer games**
Ohno, Y.; Miurs, J.; Shirai, Y.;

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 17 **Map based underwater navigation using a multibeam echosounder**
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 18 **Mapping and positioning for a prototype lunar rover**
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